

Spring Arrangement including a Spring
and Shock Absorber Assembly

Field of the Invention

5 The invention relates to a spring arrangement which includes
a spring and shock absorber assembly adjustable in elevation.

Background of the Invention

10 For the most extreme deflections and for emergency
situations (for example, a defective air spring) such air spring
and shock absorber assemblies usually include end position
buffers as stops, that is, as supports. In the deflected or
expanded position of the air spring and shock absorber assembly,
the end position buffers are already touched with slight spring
deflections. The contact engagement against the end position
15 buffers means a considerable reduction in driving comfort.
Furthermore, the repeated impact over time is associated with
high wear.

Summary of the Invention

20 It is an object of the invention to provide a spring and
shock absorber assembly which is adjustable in elevation and
wherein an impact against one or both end position buffers is
reliably avoided in the deflected state or in the expanded state.

25 The spring arrangement of the invention includes: a
plurality of spring and shock absorber assemblies; each of the
springs of the assemblies having first and second end
positions (h_1 , h_2) and being characterized by a maximum spring
deflection ($\Delta h = h_2 - h_1$); level control unit assigned to the
springs of the assemblies; sensor means operatively connected to
corresponding ones of the springs; the level control unit and the
30 sensor means coacting to determine and adjust the spring

elevation (h_x) between the first and second end positions; the shock absorbers of the assemblies having respective coefficients of friction (ρ_x); a shock absorber control unit connected to the shock absorbers of corresponding ones of the assemblies to adjust the damping hardness given by the corresponding coefficient of friction (ρ_x); and, the friction coefficient (ρ_x) of each one of the shock absorbers being a function of the spring elevation (h_x) measured for the spring associated therewith ($\rho_x = f(h_x)$).

In the foregoing, it can be seen that the object of the invention is achieved in that the damper force or the friction coefficient ρ_x of the shock absorber is controllable in dependence upon the elevation position h_x of the air spring. Accordingly, the increase of the damping force or of the coefficient of friction ρ_x of the shock absorber in the end positions of the assembly is defined as a function of the measured elevation h_x of the air spring and shock absorber assembly.

Preferably, the individual shock absorbers are so controlled in dependence upon the position of the particular air spring that the damping force is increased in at least one of the end positions, that is, the damping force of the shock absorber is increasingly hardened in the close-in range of the at least one end position.

The nonlinear characteristic line of the function is defined by a support position table which can be vehicle-specifically parameterized in accordance with pull and press stages. The pull and press stops of the air spring and shock absorber assembly are protected against damage from forces which are too large because of such an end position hardening. End position buffers can therefore be substantially eliminated.

The end position control unit according to the invention can

be a supplementary component of an air spring and shock absorber assembly control and can act in a superposing manner thereto.

An elevation displacement is easy to realize especially in air springs. For this reason, an influencing of the damping
5 force in accordance with the invention is preferably considered with respect to air spring and shock absorber assemblies.

When the shock absorber is a pressure shock absorber, then the damper hardening in the end regions can be realized by means of a pressure increase in the shock absorber. The pressure
10 adaptation is preferably generated with the aid of a pressure converter.

Brief Description of the Drawings

The invention will now be described with reference to the drawings wherein:

15 FIG. 1 is a schematic of an air spring system of a motor vehicle;

FIG. 2 is a longitudinal section of an air spring and shock absorber assembly;

20 FIG. 3 is a plot of the damping force according to the invention plotted as a function of the spring excursion;

FIG. 4a is a simplified electric block circuit diagram for the control of the air spring and shock absorber assembly in accordance with the state of the art; and,

25 FIG. 4b is an electric block circuit diagram for the control of an air spring system incorporating a damper control in accordance with the invention.

Description of the Preferred Embodiments of the Invention

The air spring system 2 of a motor vehicle shown in FIG. 1 includes four air springs (4a, 4b, 4c, 4d) which are assigned to
30 corresponding axles or wheels of the motor vehicle.

Two of the air springs (4a, 4b) are connected to each other via a first transverse line 6a and the two other air springs (4c, 4d) are connected to each other via a second transverse line 6b. The transverse line 6a includes two transverse check valves (8a, 8b) and transverse line 6b includes two transverse check valves (8c, 8d). The transverse check valves (8a, 8b, 8c, 8d) correspond to respective ones of the air springs (4a, 4b, 4c, 4d). Furthermore, the transverse lines (6a, 6b) are connected to a further line 10 via which the air springs 4a to 4d are filled with pressurized air with the aid of a compressor 12 or via which pressurized air can be released to the atmosphere via an additional valve 14. For this purpose, the control inputs of the corresponding valves 8a to 8d and the compressor 12 are controlled by a central unit 16 equipped with a level control unit 18. With the aid of the sensed elevation signals, the level control unit 18 can control the elevation of the vehicle body to a desired level independently of the state of loading.

The air spring and shock absorber assembly 22 of FIG. 2 comprises the air spring 4 with the integrated shock absorber 24.

The air spring 4 includes a cylindrical tubular flexible member 26 made of elastomeric material. The upper end of the flexible member 26 is closed off pressure-tight by the cover 28 and is attached to the chassis (not shown) of the motor vehicle.

The lower end of the flexible member 26 is attached to a roll-off piston 30 which is mounted at the wheel end via the housing of the shock absorber 24. The piston 32 of the shock absorber 24 is mounted on the chassis. The shock absorber 24 includes a damper control 34 (see FIGS. 1 and 4) having a damper actuating member 36 (FIG. 4).

For the most extreme spring deflections, the air spring and shock absorber assembly 22 is equipped with an end position buffer 38.

5 The diagram of FIG. 3 shows the damping force (more precisely, the friction coefficient ρ_x) relative to the spring excursion (the spring elevation h_x). Thus, the curve in FIG. 3 is defined by the equation:

$$\rho_x = f(h_x).$$

10 As shown in FIG. 3, the friction coefficient ρ_x increases progressively in the direction toward the end positions (h_1 , h_2) (maximum spring stroke $\Delta h = h_2 - h_1$) of the air spring 4 in accordance with the invention and increases greatly in the regions 42 close to the end positions (h_1 , h_2).

15 The block circuit diagram of FIG. 4a shows a component "damper control" 34 which is operatively connected to a damper actuating member 36. This damper actuating member 36 is the executing element for changing the damping force, more specifically, for changing the friction coefficient ρ_x of the particular damper 24. Except for a damper control unit 34 and a
20 damper actuating member 36, the central unit 16' shown here includes the electronics of the level control unit 18 which can process the signals, which are received from the elevation sensors (20a, 20b, 20c, 20d) for the purpose of adjusting the desired level. In FIGS. 4a and 4b, reference numeral 20
25 identifies the elevations sensors (20a, 20b, 20c, 20d) collectively.

Compared to the conventional circuit arrangement shown in FIG. 4a, the circuit arrangement of the invention shown schematically in FIG. 4b includes essential features, namely: the
30 component "damper control" 34 is supplemented by a component "end

position control" 40. The end-position control 40 exhibits the damper force characteristic line $\rho_x = f(h_x)$ shown in FIG. 3. This characteristic line is characterized by a progressive increase of the damping force (friction coefficient ρ_x) in a direction toward
5 the end positions (h_1, h_2) of the air spring 4.

In order to be able to output a control signal ρ_x , which corresponds to the spring elevation h_x , to the damper actuating member 36, the end-position control 40 is operatively connected to the elevation sensors 20.

10 For the case of an active damping control, the component "damper control" 34 likewise is connected to the elevation sensors 20 (see the broken line in FIG. 4b).

To control the damping force, the signals outputted by the damper control 34 and the end-position control 40 are outputted
15 to the damper actuating member 36. With the aid of the end-position control 38 according to the invention, an end-position buffer 40 (see FIG. 2) can be omitted.

It is understood that the foregoing description is that of the preferred embodiments of the invention and that various
20 changes and modifications may be made thereto without departing from the spirit and scope of the invention as defined in the appended claims.